Quarch Technology Ltd

Torridon Mini SAS Cable Pull Module

Technical Manual

For use with:

QTL1253 - Torridon Mini SAS Cable Pull Module
QTL1285 – Torridon Quad Mini SAS Cable Pull Module

Using Quarch firmware version 3.5x

Thursday, 20 May 2010

Change History

1.0	April 2010	Initial Release

Contents

Introduction

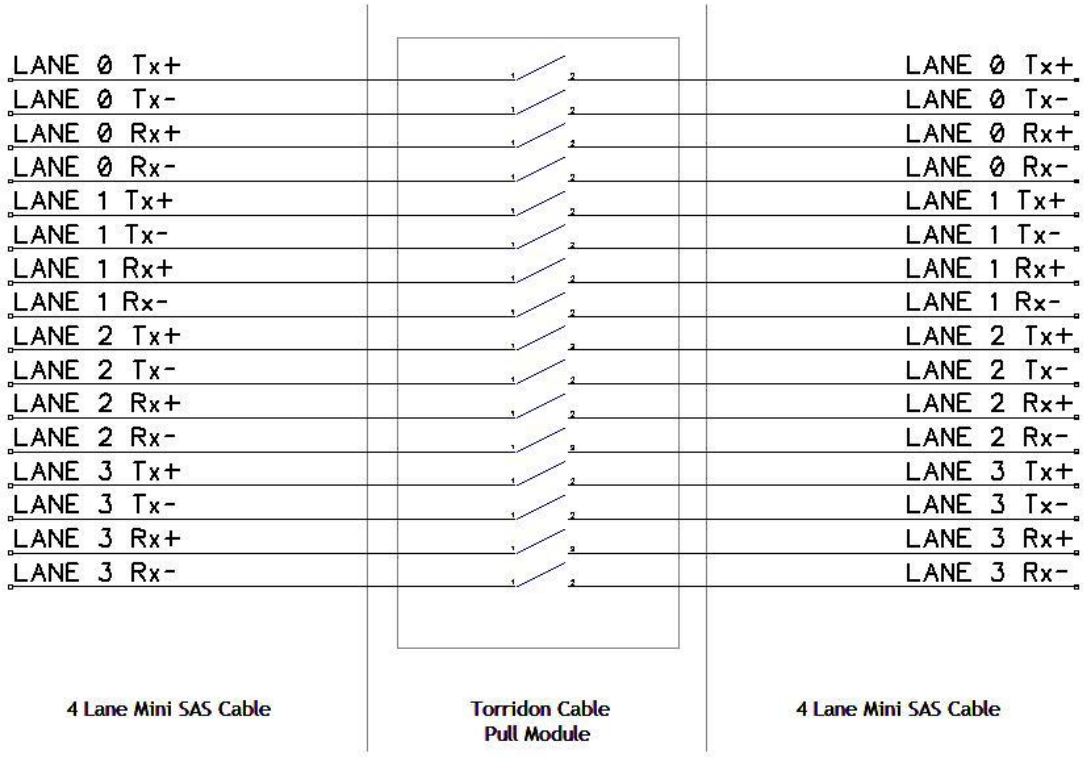
The **Torridon Mini SAS Cable Pull Module** allows remote switching of the SAS data pins in an SFF8088 Mini SAS Cable for test automation or fault injection purposes.

The module supports 1.5Gb, 3Gb and 6Gb data rates.

Each pin is individually switched, allowing complete control over the mating sequence of a cable connector.

The switches can be sequenced at precise timings to simulate a hot-swap event, including pin bounce. Individual pins can also be broken or glitched at any time to simulate a fault in the system.

Quarch modules may be customized to support other proprietary signals or form factors on request.

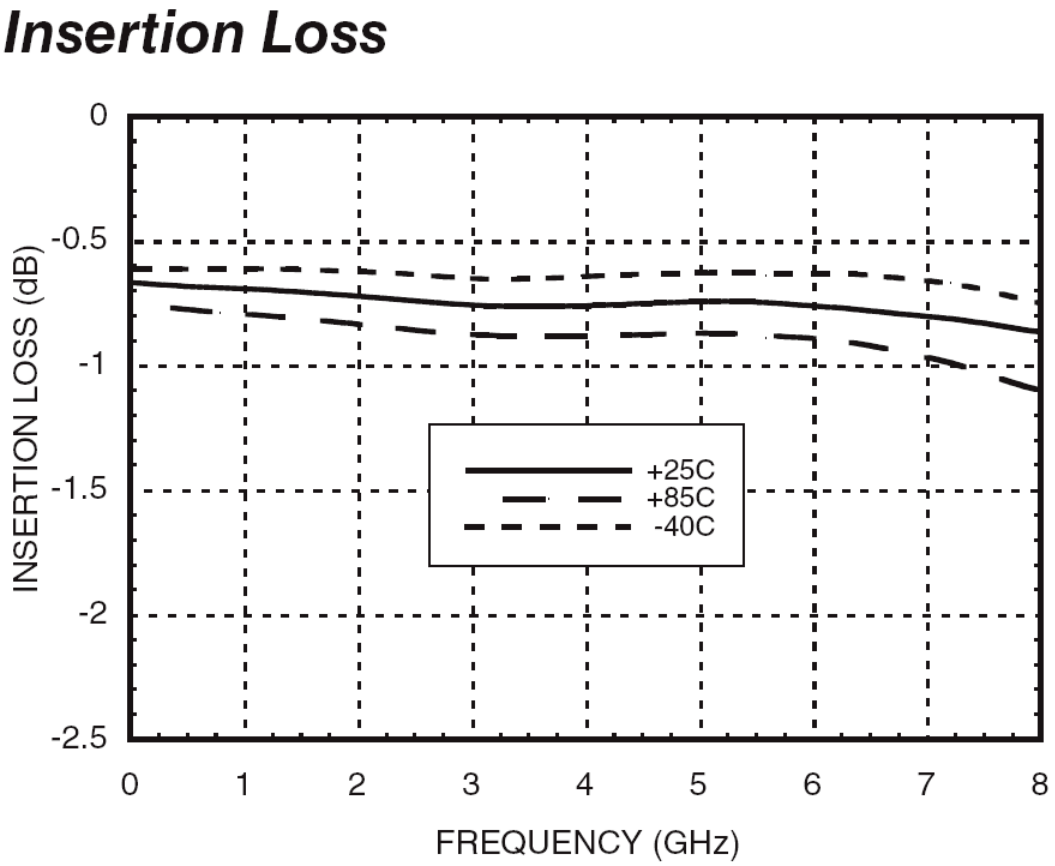


Technical Specifications

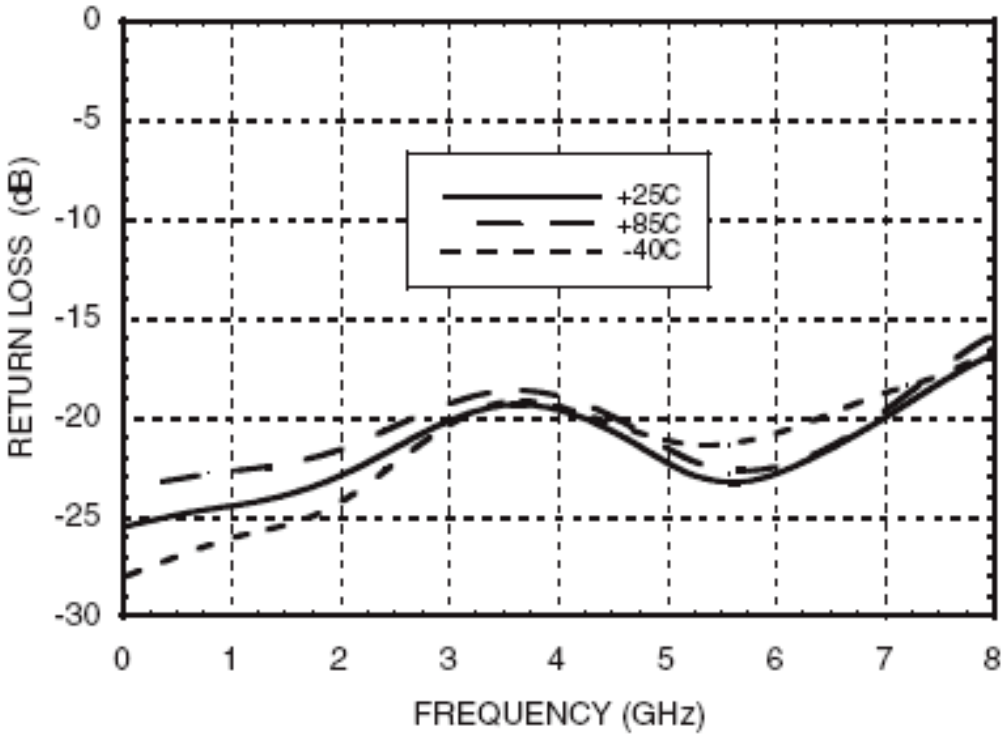
Switching Characteristics:

SAS Connector Pin	Description	Switching Action
A1,A4,A7,A10,A13, B1,B4,B7,B10,B13	Ground pins	All connected to digital Ground on the Module
A2,A3,A5,A6,A8,A9,A11,A12 B2,B3,B5,B6,B8,B9,B11,B12	SAS Data Signal pins	Each signal is individually switched by a Hittite HMC550 6GHz RF Switch

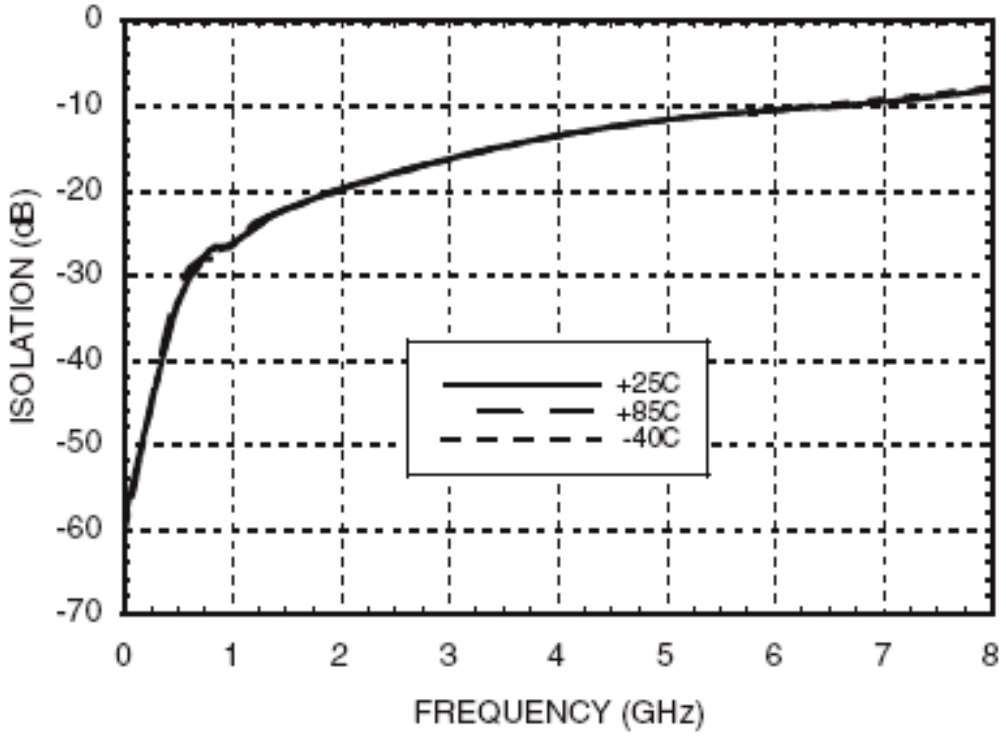
HMC550 Characteristics:



Return Loss

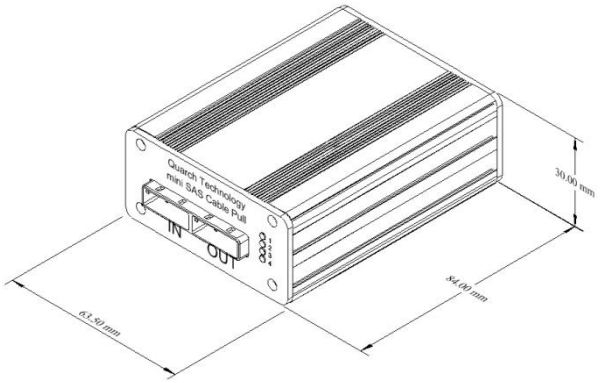


Isolation

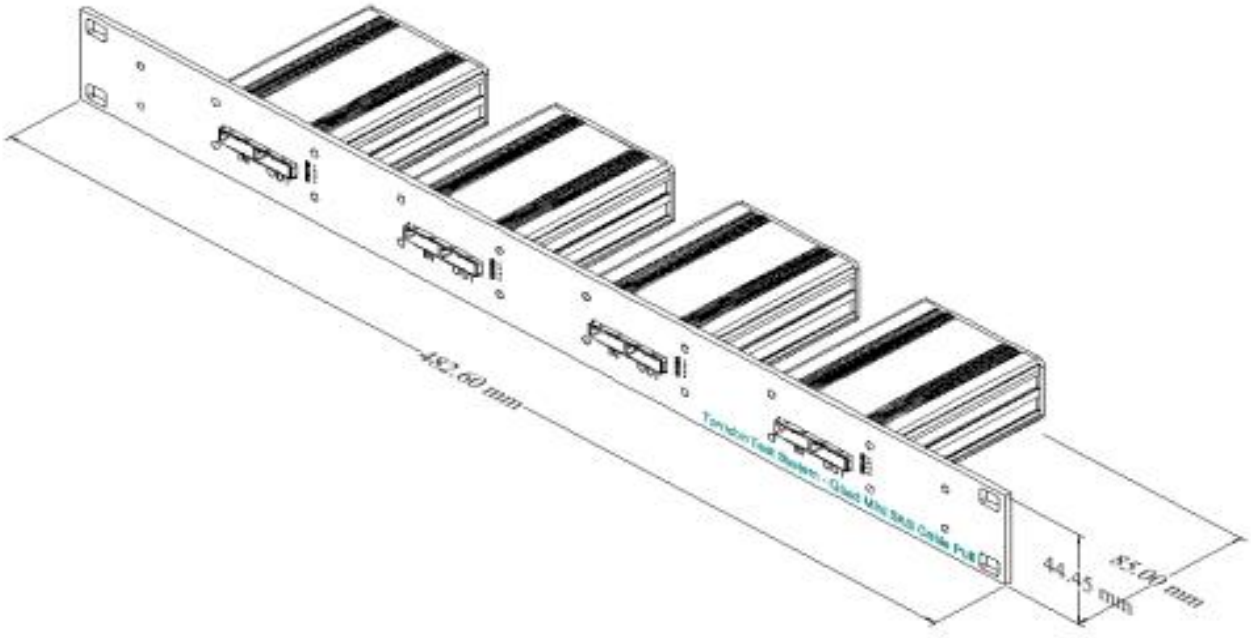


Mechanical Characteristics:

QTL1253 Mini SAS Cable Pull Module



QTL1285 Quad Mini SAS Cable Pull Module



Control Interfaces

All Torridon Control Modules are designed to be used with a Torridon Array Controller (QTL1079) or a single Torridon Interface Card (QTL1144).

The control cable is an ultra-thin Flex cable.

Control Interface	**Form Factor**	**Torridon Module Ports**	**Control Methods Available**	**Interfaces**
Torridon Array Controller	1U 19" Rack Mounted unit	24 at the front, 4 at the rear	Serial Scripting Script Generation through **TestMonkey GUI**	Serial via DB9 or RJ45 Ethernet*
Torridon Interface Card	102mm x 26mm PCB	1 port	Serial Scripting Script Generation through **TestMonkey GUI** Real-time USB Control via **TestMonkey GUI**	Serial via DB9 or RJ45 USB

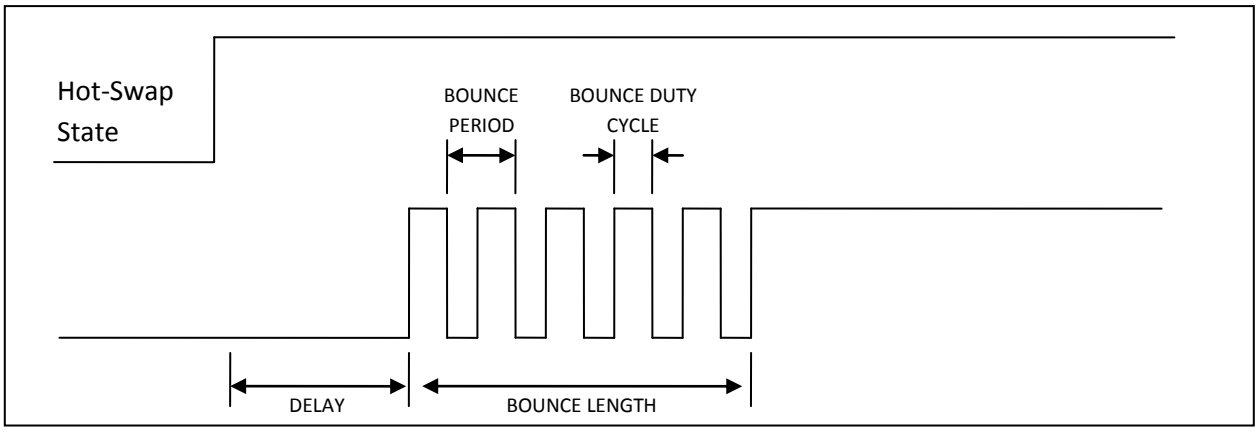
* Ethernet support will be available through firmware update in 2010 (Currently available in BETA)

Basic Concepts

Each switch on the Torridon control cards is called a 'Signal' and can be programmed to follow one of 6 programmable delay and bounce profiles (called 'Sources'). This allows the user to sequence the signal connections in the cable in up to six programmable steps.

Each of the programmable delay and bounce profiles is called a control source, S1 to S6. For each control source the user sets up a delay, and bounce parameters. Three special sources (S0, S7 and S8) are also provided as described in the table below.

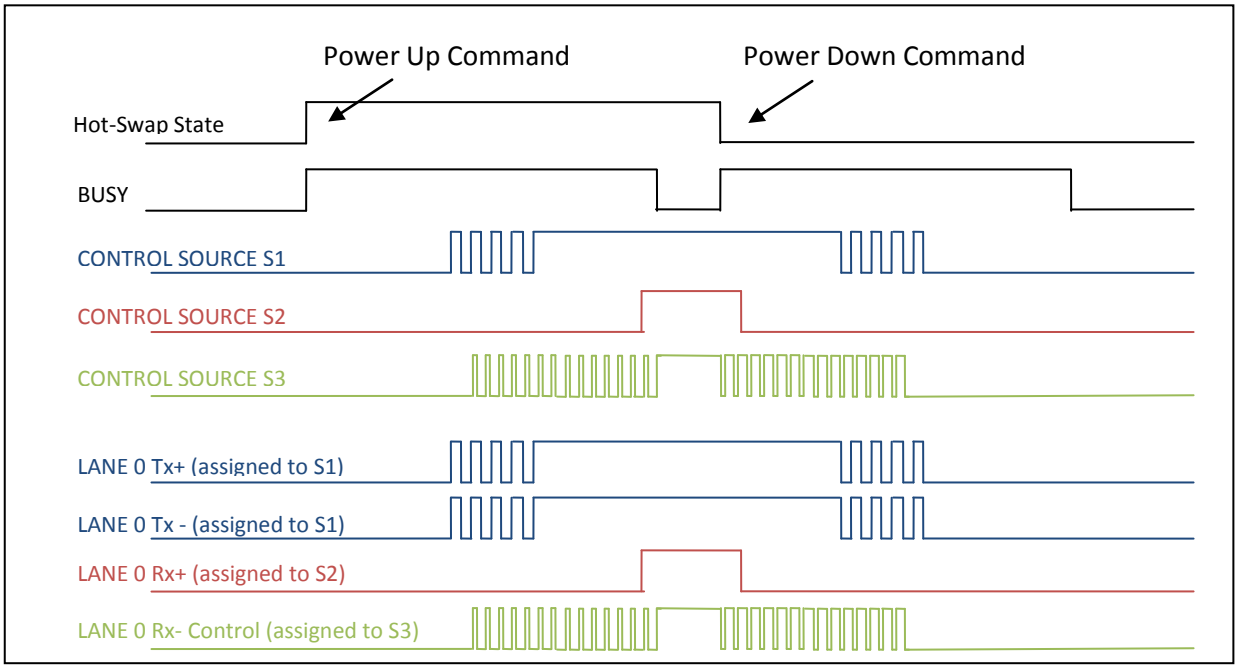
Control Source Parameters for a power up event (Basic Pin Bounce):



Once each delay period is set up, the user assigns each signal to follow the relevant control source, then uses the "run:power up" and "run:power down" commands to initiate the hot-swap.

The BUSY bit 1 in the control register is set during a power up, power down and short operation. This may be used to monitor for the completion of timed events.

Power up and Power down example:

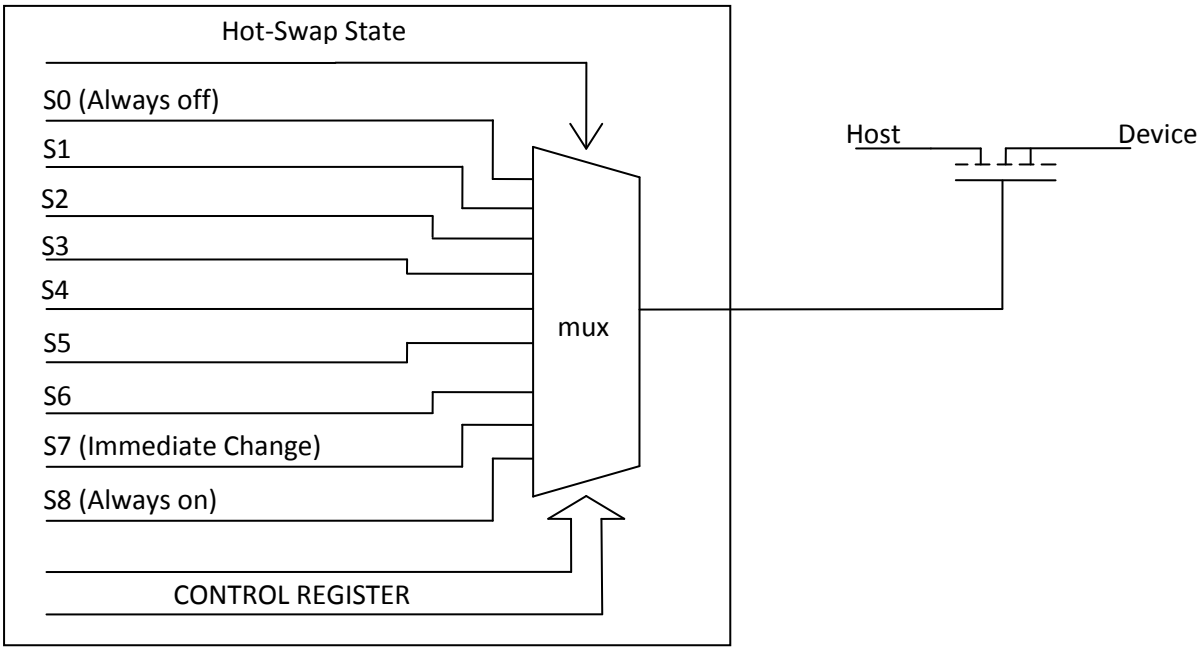


Signal Configuration

Each signal that is switched by the card is usually assigned to one of the 6 timed sources, S1 – S6. Each signal can also be assigned directly to 'always off' or 'immediate change' or 'Always on'.

To assign a signal to a control source, write to its CONTROL_REGISTER:

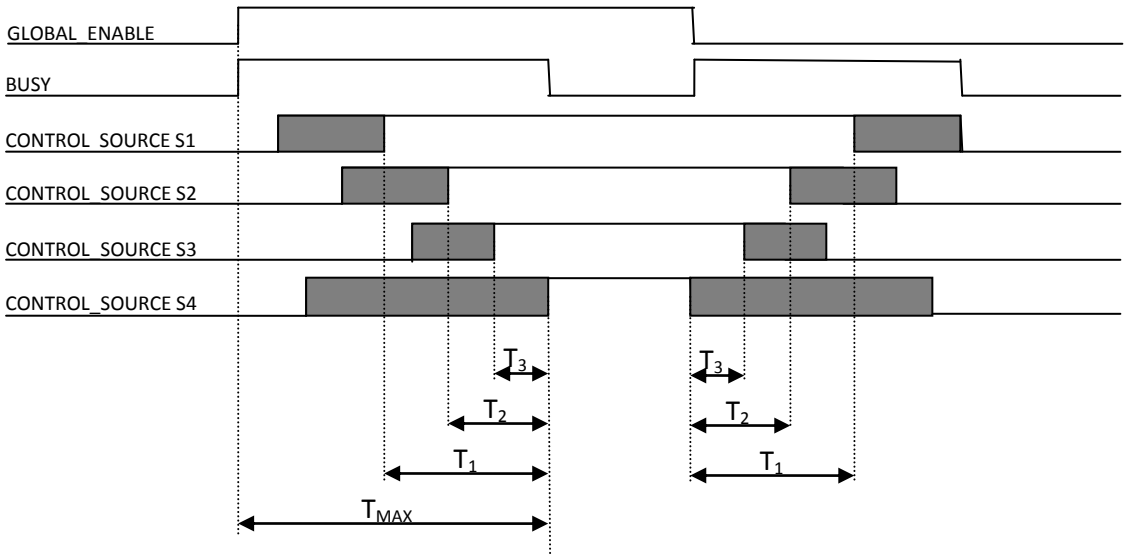
CONTROL_REGISTER Value	Description
0	Signal is always OFF
1	Signal assigned to control source 1
2	Signal assigned to control source 2
3	Signal assigned to control source 3
4	Signal assigned to control source 4
5	Signal assigned to control source 5
6	Signal assigned to control source 6
7	Signal changes with HOT_SWAP state
8	Signal is always ON



This diagram shows the 8 possible source settings entering the control MUX for a switched signal. The value of the control register will determine which of the sources are used to control the signal. When enabled, the hot-swap line will cause the MUX to pass the control signal from that source through to the switch.

Power Up vs. Power Down Timing

Each control source is always configured with power-up parameters. The power-down profile is automatically generated by the card, and is the mirror image of the power up:



Power Down Times are automatically generated by the module but can be calculated as follows:

T_{MAX} = Largest Time Period
= the largest value from: (S1_DELAY + S1_BOUNCE_LENGTH),
(S2_DELAY + S2_BOUNCE_LENGTH),

up to

(S6_DELAY + S6_BOUNCE_LENGTH)

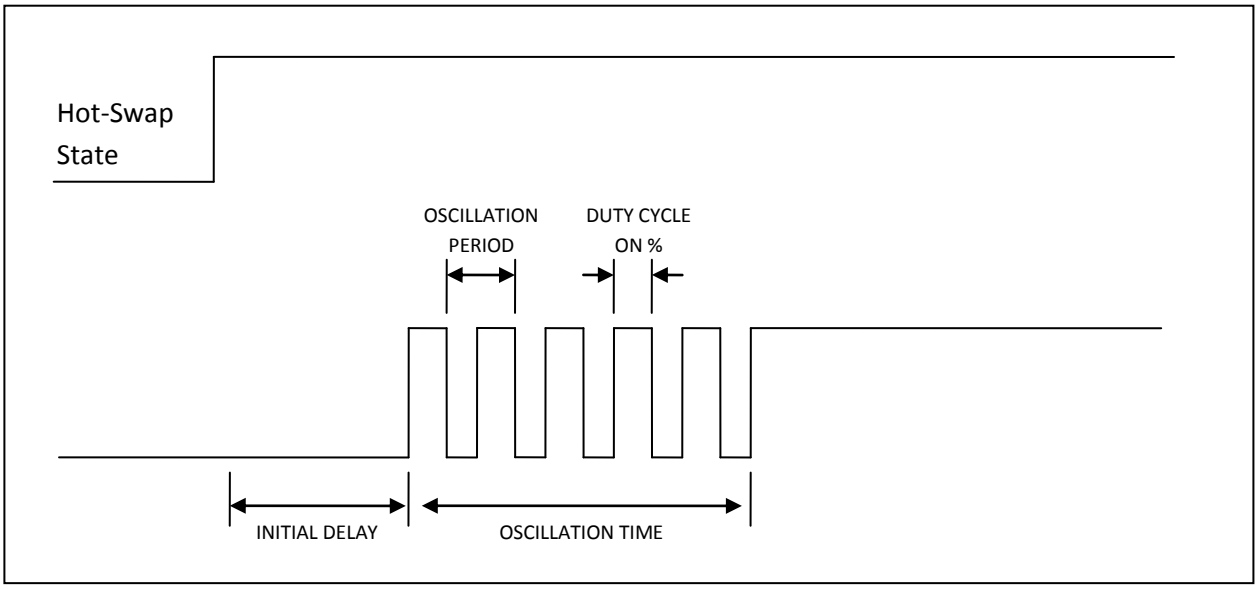
Power Down Delay T_X = T_{MAX} – (S_X_DELAY + S_X_BOUNCE_LENGTH)

If you require a different power down sequence then you can alter any of the source timing values, pin bounce or signal assignments while the module is in the plugged state. When you initiate the 'pull' action, the new settings will be used.

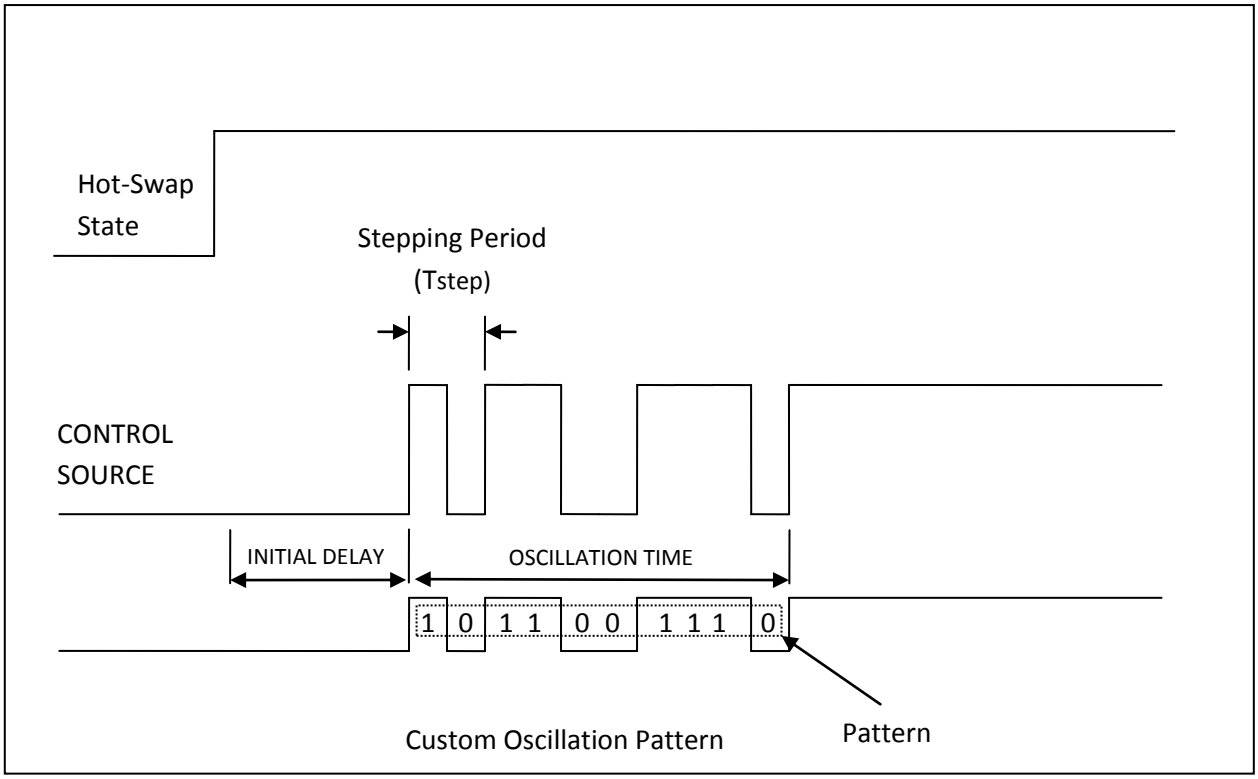
Pin Bounce Modes

Pin Bounce can be set in two ways:

1. Basic Pin-Bounce (Constant Oscillation Frequency):
   - The oscillation pattern length (Time) set in one of the two ranges:
     - 0 - 127 milliseconds in steps of 1mS
     - 0 – 1.27 seconds in steps of 10mS
   - The bounce period is for the pattern (T_{OSC}) is set on one of the two ranges:
     - 0 - 1.27 milliseconds in steps of 10uS
     - 0 – 127 milliseconds in steps of 1mS
   - The Duty cycle (On %) is set as a percentage value in the range 1-99%



2. User Pin-Bounce (Custom Oscillation):
   - The oscillation pattern length (Time) set in one of the two ranges:
     - 0 - 127 milliseconds in steps of 1mS
     - 0 – 1.27 seconds in steps of 10mS
   - The stepping period (Tstep)is for the pattern is set on one of the two ranges:
     - 0 - 1.27 milliseconds in steps of 10uS
     - 0 – 127 milliseconds in steps of 1mS
   - The Custom pattern is described in 100 bits, where 2 bits are stepped through in each Tstep period. The 100 bit pattern will loop if the oscillation pattern time is longer than the available pattern.



Glitch Control

Any control signal may be glitched for a pre-determined length of time using the glitch generator logic.

Each Signal Control register contains a "GLITCH_ENABLE" bit which determines whether the glitch logic will affect that signal. The GLITCH ENABLE bit, defaults to off, so any glitches will have no effect unless explicitly set to do so.

Glitches will invert the current state of the switched signal. Therefore if a switch is currently OFF, a glitch will turn it ON, and if the switch is ON, it will turn OFF.

Glitches may be applied in 3 modes:

Glitch Once:

A single glitch is generated when the **RUN**:**GLITch ONCE** command is executed

The length of the glitch is determined by using the **GLITch:SETup** command or the **GLITch:MULTiplier and GLITch:LENgth** commands.

PULSE LENGTH = GLITch:MULTiplier x GLITch:LENgth

Repeated use of the **RUN:GLITch: ONCE** command will generate multiple glitches, it is not necessary to use the **RUN:GLITch OFF** command after a single glitch.

Glitch Cycle:

A sequence of glitches is generated when the **RUN:GLITch CYCLE** command is executed, and continues until **RUN:GLITch OFF** is executed.

The length of the glitch is determined by using the **GLITch:SETup** command or the **GLITch:MULTiplier** and **GLITch:LENgth** commands:

PULSE LENGTH = GLITch:MULTiplier x GLITch:LENgth

The length of time between each glitch pulse is determined by the **GLITch:MULTiplier** and **GLITch:CYCLE** commands:

OFF TIME = GLITch:MULTiplier x GLITch:CYCLE

Glitch PRBS:

A pseudo random sequence of glitches is generated when the **RUN:GLITch PRBS** command is executed, and continues until **RUN:GLITch OFF** is executed.

The length of the glitch is determined by using the **GLITch:SETup** command or the **GLITch:MULTiplier and GLITch:LENGTH** commands:

PULSE LENGTH = GLITch:MULTiplier x GLITch:LENgth

The number of glitches in a set length of time is determined by the **GLITch:PRBS** command. A value of 2 will result in glitches at a ratio of 1:2 (the line will be in a glitched state 50% of the time), whilst a value of 256 will produce glitches in a ratio of 1:256.

Voltage Measurements

The modules are capable of measuring various voltages both for self test and to assist in the testing of a customer's system. The following measurement points are available:

Measurement Command	Description	Resolution / Accuracy
MEASure:VOLTage:SELF 1v2?	Returns the voltage of the modules internal 1.2v power rail	64mV / 5%
MEASure:VOLTage:SELF 3v3?	Returns the voltage of the modules internal 3.3v power rail	64mV / 5%
MEASure:VOLTage:SELF 5v?	Returns the voltage of the modules internal 5v power rail	64mV/ 5%

Default Startup State

On power up or reset, the control modules enter a default state. On the cable pull module all signals are connected at startup. The “run:power down” command will immediately disconnect the cable without needing any initial setup.

The default hot-swap scenario will disconnect all pins immediately, without delays or pin-bounce.

Source Number	Initial Delay	Pin Bounce Mode	Bounce Length	Bounce Period	Bounce Duty Cycle
1	0mS	Standard	0mS	0uS	50%
2	0mS	Standard	0mS	0uS	50%
3	0mS	Standard	0mS	0uS	50%
4	0mS	Standard	0mS	0uS	50%
5	0mS	Standard	0mS	0uS	50%
6	0mS	Standard	0mS	0uS	50%

Signal	Assigned Source
Lane 0 Tx+	Source 1
Lane 0 Tx-	Source 1
Lane 0 Rx+	Source 1
Lane 0 Rx-	Source 1
Lane 1 Tx+	Source 1
Lane 1 Tx-	Source 1
Lane 1 Rx+	Source 1
Lane 1 Rx-	Source 1
Lane 2 Tx+	Source 1
Lane 2 Tx-	Source 1
Lane 2 Rx+	Source 1
Lane 2 Rx-	Source 1
Lane 3 Tx+	Source 1
Lane 3 Tx-	Source 1
Lane 3 Rx+	Source 1
Lane 3 Rx-	Source 1

Hot-Swap State:
The cable is in the ‘plugged’ state, waiting for a **RUN:POWer DOWN** command to disconnect it.

Controlling the Module

Torridon Modules can be controlled either by:

- Serial ASCII terminal (such as HyperTerminal)
  This is normally used with scripted commands to automate a series of tests. The commands are normally generated by a script or user code (PERL, TCL, C, C# or similar).

- USB
  Quarch's TestMonkey application can control a single module via USB, this allows simple graphical control of the module.

Serial Command Set

When connected via a serial terminal, the cable pull modules have a simple command line interface

SCPI Style Commands

These commands are based on the SCPI style control system that is used by many manufacturers of test instruments. The entire SCPI specification has NOT been implemented but the command structure will be very familiar to anyone who has used it before.

- SCPI commands are NOT case sensitive
- SCPI commands are in a hierarchy separated by ':' (LEVel1:LEVel2:LEVel3)
- Most words have a short form (e.g. 'register' shortens to 'reg'). This will be documented as REGister, where the short form is shown in capitals.
- Some commands take parameters. These are separated by spaces after the main part of the command (e.g. "meas:volt:self 3v3?" Obtains the 3v3 self test measurement)
- Query commands that return a value all have a '?' on the end
- Commands with a preceding '*' are basic control commands, found on all devices
- Commands that do not return a particular value will return "OK" or "FAIL". Unless disabled, the fail response will also append a text description for the failure if it can be determined.

 # [comments]

Any line beginning with a # character is ignored as a comment. This allows commenting of scripts for use with the module.

***RST**

Triggers a reset, the module will behave as if it had just been powered on

***CLR**

Clear the terminal window and displays the normal start screen. Also runs the internal self test. The same action can be performed by pressing return on a blank line.

***IDN?**

Displays a standard set of information, identifying the device. An example return is shown below

Family:	Torridon System	[The parent family of the device]
Name:	Mini SAS Cable Pull Module	[The name of the device]
Part#:	QTL1253-01	[The part number of the hardware]
Processor:	QTL1159-01,3.50	[Part# and version of firmware]
Bootloader:	QTL1170-01,1.00	[Part# and version of bootloader]
FPGA 1:	1.0	[Version of FPGA core]

***TST?**

Runs a set of standard tests to confirm the device is operating correctly, these tests are also performed at start up. Returns 'OK' or 'FAIL' followed by a list of errors that occurred, each on a new line.

CONFig:MODE BOOT

Configures the card for boot loader mode (to update the firmware), requires an update utility on the PC.

CONFig:MESSages [SHORt|USER]
CONFig:MESSages?

Gets or sets the mode for messages that are returned to the user's terminal

Short: Only a "FAIL" or "OK" will be returned
User: Full error messages are returned to the user on failure

REGister:READ [0xAA]

Returns the value of the register with address [0xAA]. [0xAA] should be in hex format and preceded by the suffix "0x". e.g. "0x6D" or "0x006D". The value is returned in the same form as the address.

REGister:DUMP [0xA1] [0xA2]

Returns the value of each register in a range, starting at the first register address, up to the second. [0xA1] and [0xA2] should be in hex format and preceded by the suffix "0x". Each data value will be returned on a new line.

REGister:WRITe [0xAAAA] [0xDDDD]

Writes the byte [0xDD] to register [0xAAAA], both [0xDDDD] and [0xAAAA] should be in hex format and preceded by the suffix “0x”. The command returns “OK” or “FAIL”.

RUN:POWer [UP|DOWN]

Initiates a plug or pull operation (legacy name used to preserve compatibility between Torridon modules). This is done by changing the HOT_SWAP bit, register 0x00 bit 0. This is the master control for all switches on the card. The same action can be performed by writing this bit directly.

The command will fail if you order a power up when the module is already in the connected state and vice-versa as the action cannot be performed.

The “OK” response will be returned as soon as the hot-swap event has begun. If your timing sequence is very long you may have to poll the BUSY bit in register 0 to check when it has completed.

MEAS:VOLTage:SELF [1.2?|3v3?|5v?]

Returns the self test voltages. These are measurements of voltage rails required for correct operation of the module. The values are returned in the form “5000mV”

SOURce:[1-6|ALL]:SETup [#1] [#2] [#3] [#4]

Sets up the source in a single command. All parameters are positive decimal numbers:
#1 = Initial delay (mS)
#2 = Bounce length (mS)
#3 = Bounce Period (uS)
#4 = Duty Cycle (%)

SOURce:[1-6|ALL]:DELAY [#ms]
SOURce:[1-6|ALL]:DELAY?

Sets the initial delay of a source in mS. The delay is entered as a decimal number with no units. E.g. “Source:1:delay 300”.

SOURce:[1-6|ALL]:BOUNce:SETup [#1] [#2] [#3]

Sets up the bounce parameters in a single command. All parameters are positive decimal numbers:
#1 = Bounce length (mS)
#2 = Bounce Period (uS)

#3 = Duty Cycle (%)

SOURce:[1-6|ALL]:BOUNce:LENgth [#ms]
SOURce:[1-6|ALL]:BOUNce:LENgth?

Sets the length of the pin bounce in mS. The delay is entered as a decimal number with no units. E.g. “Sour:2:boun:len 50”. Due to hardware limitations, the exact value you request may not be available. In this case, the nearest value will be used. See “Timing Limitations” for details.

SOURce:[1-6|ALL]:BOUNce:PERiod [#us]
SOURce:[1-6|ALL]:BOUNce:PERiod?

Sets the bounce period of the pin bounce in uS. The value is entered as a decimal number with no units. E.g. “Sour:6:boun:period 300”. Due to hardware limitations, the exact value you request may not be available. In this case, the nearest value will be used. See “Timing Limitations” for details.

SOURce:[1-6|ALL]:BOUNce:DUTY [#%]
SOURce:[1-6|ALL]:BOUNce:DUTY?

Sets the duty cycle of the pin bounce as a %. The value is entered as a decimal number with no units. E.g. “source:3:bounce:duty 50”.

SOURce:[1-6|ALL]:BOUNce:CLEAR

Removes any pin bounce from the source and sets all bounce settings to default values. See “Startup State” for details for the default settings.

SIGnal:[SIG_NAME|ALL]:SETup [#num]
SIGnal:[SIG_NAME|ALL]:SOURce [#num]

Sets a given signal to a numbered timing source (0-8). SIGNAL_NAME is one of the following signals that can be switched by the cable pull module:

TX0_PL	(Data transmitted from the ‘input’ port on Lane 0 (+ve side of differential pair)
TX0_MN	
RX0_PL	(Data received at the ‘input’ port on Lane 0 (+ve side of differential pair)
RX0_MN	
TX1_PL	
TX1_MN	
RX1_PL	
RX1_MN	
TX2_PL	
TX2_MN	

RX2_PL
RX2_MN
TX3_PL
TX3_MN
RX3_PL
RX3_MN

Signal groups are used to alter the state of multiple Signals as the same time. Only commands that alter a setting can use signal groups. Commands that return a setting value do not support signal groups as there is no single value to return.

ALL	(Affects all signals)
LANE0	(Affect all signals relating to a specific SAS lane)
LANE1	
LANE2	
LANE3	

SIGnal:[SIG_NAME|ALL]:GLITch:ENAble [ON|OFF]
SIGnal:[SIG_NAME|ALL]:GLITch:ENAble?

Enables a signal for glitching. If this in on, the signal will be glitched whenever the glitch logic is in use. Multiple signals may be set for glitch at the same time.

RUN:GLITch ONCE

Triggers a single glitch

RUN:GLITch CYCLE

Starts a cycling glitch sequence

RUN:GLITch PRBS

Starts a PRBS glitch sequence

RUN:GLITch STOP

Stops any running sequence of glitching

GLITch:SETup [MULTIPLIER_STEP] [#count]

Sets up the glitch time in a single command.
MULTIPLIER_STEP = One of the multiplier step values from the command below
#count = The length of the glitch in steps

GLITch:MULTiplier [50ns|500sn|5us|50us|500us|5ms|50ms|500ms]
GLITch:MULTiplier?

Sets the multiplier step value for the glitch time. A wide range or multipliers is supplied to allow a full range of glitch lengths. This factor is combined with the 'glitch length' value to give the actual glitch time

GLITch:LENgth [#count]
GLITch:LENgth?

Sets the length of the glitch. This is multiplied up by the 'glitch multiplier' to give the final time of the glitch

GLITch:CYCLE [#gap_count]

Sets the cycle counter for cycling repeat glitches, a value of 1 means the glitch logic is off for the same length of time it's on, 2 mean's its off for twice the time that it's on.

GLITch:PRBS [2|4|8|16|32|64|128|256]

Sets the PRBS rate for Pseudo Random repeat glitching, this is a ratio, 2 means 1:2 (approximately 50% of the time the signal will be glitched), 256 means 1:256.

CONFig:TERMinal USER

Sets the terminal response mode to the default 'User' setting. This is intended for use with HyperTerminal or similar and manually typed commands

CONFig:TERMinal SCRIPT

Sets the terminal response mode for easier parsing. Especially useful from a UNIX/LINUX based system. Characters sent from the PC are not echoed by the device and a <CR><LF> is sent after the cursor to force a flush of the USART buffer.

CONFig:TERMinal ?

Returns the current terminal mode

Control Register Map

Access to the FPGA registers should not be required for the majority of operations and customers are encouraged to use the high level commands in order to maintain compatibility with future firmware versions. It is listed here for reference / debug purposes.

Address	Name	Description
0x00	Global Control	Trigger Power up/down and Glitch
0x01	Glitch Control	Glitch Length and Cycle Time
0x02	Reserved	Reserved
0x03	Reserved	Reserved
0x04	Reserved	Reserved
0x05	S1 Initial Delay & Bounce Period	Delay 0 to 1s / Period 0 to 100mS
0x06	S1 Bounce Length & Duty Cycle	0 to 1s / 0 to 100%
0x0D..0x07	S1 Custom Pattern	112 bit pattern
0x0E	S2 Initial Delay & Bounce Period	Delay 0 to 1s / Period 0 to 100mS
0x0F	S2 Bounce Length & Duty Cycle	0 to 1s / 0 to 100%
0x16..0x10	S2 Custom Pattern	112 bit pattern
0x17	S3 Initial Delay & Bounce Period	Delay 0 to 1s / Period 0 to 100mS
0x18	S3 Bounce Length & Duty Cycle	0 to 1s / 0 to 100%
0x1F..0x19	S3 Custom Pattern	112 bit pattern
0x20	S4 Initial Delay & Bounce Period	Delay 0 to 1s / Period 0 to 100mS
0x21	S4 Bounce Length & Duty Cycle	0 to 1s / 0 to 100%
0x28..0x22	S4 Custom Pattern	112 bit pattern
0x29	S5 Delay & Bounce Period	Delay 0 to 1s / Period 0 to 100mS
0x2A	S5 Bounce length & DutyCycle	0 to 1s / 0 to 100%
0x31..0x2B	S5 Custom Pattern	112 bit pattern
0x32	S6 Delay & Bounce Period	Delay 0 to 1s / Period 0 to 100mS
0x33	S6 Bounce Length & Duty Cycle	0 to 1s / 0 to 100%
0x3A..0x34	S6 Custom Pattern	112 bit pattern
0x6C	LED Status	LED Status Register
0x6D	TX0_PL	Signal Assignment Register
0x6E	TX0_MN	Signal Assignment Register
0x6F	RX0_PL	Signal Assignment Register
0x70	RX0_MN	Signal Assignment Register
0x71	TX1_PL	Signal Assignment Register
0x72	TX1_MN	Signal Assignment Register
0x73	RX1_PL	Signal Assignment Register
0x74	RX1_MN	Signal Assignment Register
0x75	TX2_PL	Signal Assignment Register
0x76	TX2_MN	Signal Assignment Register

0x77	RX2_PL	Signal Assignment Register
0x78	RX2_MN	Signal Assignment Register
0x79	TX3_PL	Signal Assignment Register
0x7a	TX3_MN	Signal Assignment Register
0x7b	RX3_PL	Signal Assignment Register
0x7c	RX3_MN	Signal Assignment Register
0xFE	FPGA PART NUMBER	FPGA Part Number Register
0xFF	FPGA VERSION	FPGA Code Version Register

Register Definitions

0x00 - Global Control

15	14	13	12	11	10	9	8
					GLITCH_PRBS	GLITCH_CYCLE	GLITCH_TRIGGER

7	6	5	4	3	2	1	0
						BUSY	HOT_SWAP

Name	Description
GLITCH_PRBS	Selects PRBS glitch mode. When set, this bit overrides GLITCH_CYCLE
GLITCH_CYCLE	Selects Glitch cycle mode when set, glitch once mode when clear
GLITCH_TRIGGER	Set this signal to start a single glitch, or a glitch cycle, clear this signal to stop a glitch cycle
BUSY	This bit is cleared when the card is in a steady state, i.e. all delays/pin bounce/glitches are completed
GLOBAL_ENABLE	All Switches are enabled when this bit is set, otherwise all power is off

0x01 - Glitch Control

15	14	13	12	11	10	9	8
GLITCH_CYCLE_MULTIPLIER	GLITCH_CYCLE						

7	6	5	4	3	2	1	0
GLITCH_MULTIPLIER			GLITCH_LENGTH				

Name	Description
GLITCH_LENGTH	Set the number of steps to glitch for
GLITCH_MULTIPLIER	Change step size, 0 = 50nS, 1 = 500ns, 2= 5us,3=50us,4=500us,5=5ms,6=50ms,7=500ms
GLITCH_CYCLE	Number of steps to stay off for
GLITCH_CYCLE_MULTIPLIER	Multiply GLITCH_CYCLE by 10 when set

0x02 – Glitch PRBS Control

15	14	13	12	11	10	9	8
0	0	0	0	0	0	0	0

7	6	5	4	3	2	1	0
0	0	0	0	0	GLITCH_PRBS_DUTY		

Name	Description
GLITCH_PRBS_DUTY	Set the “on percentage” of the PRBS signal 0 = 1 in 256 steps is glitched 1 = 1 in 128 steps is glitched 2 = 1 in 64 steps is glitched 3 = 1 in 32 steps is glitched 4 = 1 in 16 steps is glitched 5 = 1 in 8 steps is glitched 6 = 1 in 4 steps is glitched 7 = 1 in 2 steps is glitched

Source Registers

Each source is setup by a block of 9 16-bit wide registers. Below is the register map for a generic source. The list of registers in the title indicates the actual address of the byte in each of the 6 timed sources.

Source Delay & Bounce Period
[0x05,0x0E,0x17,0x20,0x29,0x32]

15	14..8	7	6..0
Sx_BOUNCE_PERIOD_MULTIPLIER	Sx_BOUNCE_PERIOD	Sx_DELAY_MULTIPLIER	Sx_DELAY

Name	Description
Sx_DELAY_MULTIPLIER	When 0, Delay Multiplier is 1mS When 1, Delay Multiplier is 10mS
Sx_DELAY	The Total delay between the global enable being set or start of a power cycle event and the signal beginning to mate T_{DELAY} = xV_DELAY x xV_DELAY_MULTIPLIER i.e. 00000010 = 2mS, 10001001 = 90mS
Sx_BOUNCE_PERIOD_MULTIPLIER	When 0, Delay Multiplier is 10uS When 1, Delay Multiplier is 1mS
Sx__BOUNCE_PERIOD	The Period of the bounce frequency when pin-bounce is enabled Period = xV_BOUNCE_PERIOD x xV_BOUNCE_PERIOD_MULTIPLIER i.e. 00000010 = 20uS, 10001001 = 9mS

Source Bounce Mode, Bounce Length & Bounce Duty Cycle
[0x06,0x0F, 0x18, 0x21, 0x2A, 0x33]

15	14..8	7	6..0
Sx_PIN_BOUNCE_MODE	Sx_BOUNCE_DUTY_CYCLE	Sx_BOUNCE_TIME_MULTIPLIER	Sx_BOUNCE_TIME

Name	Description
Sx_BOUNCE_TIME_MULTIPLIER	When 0, Delay Multiplier is 1mS When 1, Delay Multiplier is 10mS
Sx_BOUNCE_TIME	The period of the bounce frequency when pin-bounce is enabled T_{BOUNCE} = xV_BOUNCE_TIME x xV_BOUNCE_TIME_MULTIPLIER i.e. 00000010 = 2mS, 10001001 = 90mS
Sx_BOUNCE_DUTY_CYCLE	The Duty Cycle of the bounce frequency, expressed as a percentage Values 0 – 100 are valid
Sx_PIN_BOUNCE_MODE	When 1, Custom Pin Bounce Mode is Enabled

Source Custom Pattern
[0x0D..0x07, 0x16..0x10, 0x1F..0x19, 0x28..0x22, 0x31..0x2B, 0x3A..0x34]

Offset	Bits
6	111..96
5	95..80
4	79..64
3	63..48
2	47..32
1	31..16
0	15..0

Name	Description
Sx_CUSTOM_PATTERN	The 112 bit custom pattern is held in 7 sequential registers

LED Status Registers

0x6C – LED Status

15	14	13	12	11	10	9	8
0	0	0	0	0	0	0	0

7	6	5	4	3	2	1	0
LANE3 ORANGE	LANE3 GREEN	LANE2 ORANGE	LANE2 GREEN	LANE1 ORANGE	LANE1 GREEN	LANE0 ORANGE	LANE0 GREEN

Name	Description
LANE0 GREEN	set when the LANE 0 GREEN LED is on
LANE0 ORANGE	set when the LANE 0 ORANGE LED is on
LANE1 GREEN	Set when the LANE 1 GREEN LED is on
LANE1 ORANGE	Set when the LANE 1 ORANGE LED is on
LANE 2 GREEN	Set when the LANE 2 GREEN LED is on
LANE 2 ORANGE	Set when the LANE 2 ORANGE LED is on
LANE 3 GREEN	Set when the LANE 3 GREEN LED is on
LANE 3 ORANGE	Set when the LANE 3 ORANGE LED is on

Signal Registers

Each signal is controlled by a single register. The low 4 bits of the register stores a single number that describes which source the signal should be following.

Each register assigns the named signal to one of the six control sources, on with global enable, always off, or always on:

Nibble Value	Assigned Control Source
0	Always OFF
1	Follow Source S1
2	Follow Source S2
3	Follow Source S3
4	Follow Source S4
5	Follow Source S5
6	Follow Source S6
7	ON when Hot-Swap state is high
8	Always ON

Signal Control

15	14	13	12	11	10	9	8
0	0	0	0	0	0	0	GLITCH ENABLE

7	6	5	4	3..0
0	0	0	0	SIGNAL CONTROL SOURCE

Name	Description
SIGNAL CONTROL SOURCE	1-6 Sets control source for this signal, 0 is always off, 7 on with power up, and 8 always on
GLITCH_ENABLE	Enables the glitch logic to control this signal

Other Registers

0xFE – CPLD Part Number Register

15..0
4 digit CPLD part number

Name	Description
PART_NUMBER	Forms the QTLnnnn part number

0xFF – CPLD Version Register

15..8	7..0
MAJOR REVISION	MINOR REVISION

Name	Description
MAJOR_REVISION	Should read as 1 or higher
MINOR_REVISION	Should read as 0 or higher

Appendix 1 - Signal Names

The following signal names are used to specify a single signal or a group of signals. These may be used in commands that take a parameter “SIGNAL_NAME”. Note that some commands, such as those returning a value, only accept a parameter that resolves to a single signal. In this case you cannot use the group names

Signals

TX0_PL (Data transmitted from the ‘input’ port on Lane 0 (+ve side of differential pair)
TX0_MN
RX0_PL (Data received at the ‘input’ port on Lane 0 (+ve side of differential pair)
RX0_MN
TX1_PL
TX1_MN
RX1_PL
RX1_MN
TX2_PL
TX2_MN
RX2_PL
RX2_MN
TX3_PL
TX3_MN
RX3_PL
RX3_MN

Signal Groups

ALL (Allows change of all signals at the same time)
LANE0 (Affect all signals relating to a specific SAS lane)
LANE1
LANE2
LANE3